LLM-Guided Autoscheduling for Large-Scale Sparse Machine Learning

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Abstract

Optimizing sparse machine learning (ML) workloads requires navigating a vast schedule space. Two of the most critical aspects of that design space include *which operators to fuse* and *which loop/dataflow order* to use within each fused region. We present AUTOSPARSE, an LLM-guided autoscheduler atop FuseFlow, a sparse ML compiler that focuses on *fusion grouping* and *legal dataflow order* selection. FuseFlow enumerates lawful orders per fused region and exposes a lightweight FLOPs/byte signal; the LLM proposes structured candidates (fusion sets and orders) that we validate and rank before codegen. With backend defaults for blocking and parallelism held fixed, case studies on GCN, GraphSAGE show consistent gains over unfused baselines and parity with hand-tuned/heuristic schedules. Coupling LLM reasoning with FuseFlow's legality guards and roofline-style signals efficiently explores sparse scheduling spaces with minimal human effort.

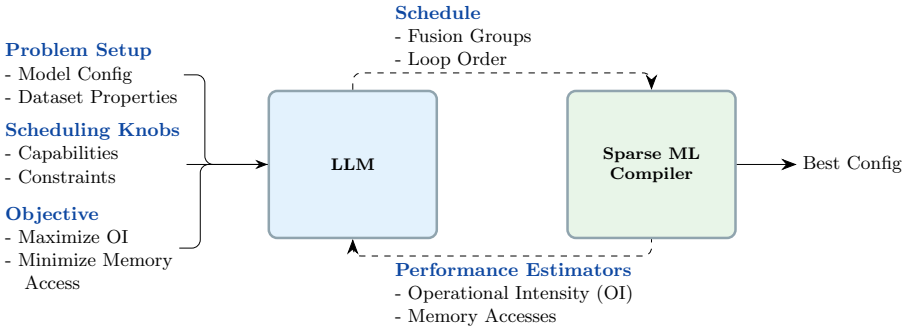

Figure 1: Overview of AUTOSPARSE: the LLM proposes schedules; the compiler validates, enumerates legal dataflow orders, and returns cost estimates; the best configuration is then selected.

1 Introduction

Sparse deep learning models are hard to optimize because of irregular memory access and vast scheduling spaces. High performance usually requires expert decisions about which operations to fuse to cut memory traffic, which dataflow order to use, how to tile to fit fast memory, and how to parallelize. Manual exploration is infeasible for full models. Autoschedulers in dense settings (e.g., Halide, TVM) have been successful [13; 2], but sparse models add combinatorial dataflow choices

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and sparsity-specific constraints that make search harder [11; 1; 14]. Dataflow accelerators for sparse workloads further increase the payoff of getting fusion and dataflow order right [8; 7].

Fusion is a first-order lever for performance. By co-iterating producers/consumers and avoiding materialized intermediates, the right fusion granularity increases operational intensity and can change the algorithmic cost (work and I/O), yielding asymptotic efficiency gains when traversal aligns with sparse storage format [16].

We propose to leverage LLMs to co-pilot the scheduling process. Our *LLM-guided autoscheduler* works with FuseFlow [12], a fusion-centric sparse ML compiler implemented in MLIR that targets SAM-style dataflow graphs. FuseFlow can fuse any subset of expressions given a user *Fuse* schedule, then enumerates all *legal* dataflow orders and exposes a lightweight FLOPs/byte heuristic. The autoscheduler feeds a textual description of the compute graph, the compiler's knobs (fuse sets and dataflow orders), and hardware hints to an LLM, asking for concrete schedule proposals and reasoning. Candidate schedules are validated against compiler invariants and scored using the heuristic; poor candidates are pruned before code generation.

LLMs have shown promise in compiler optimization by reasoning over large discrete spaces and leveraging prior knowledge [9; 6; 3]. For sparse ML, schedule quality hinges on long-range trade-offs (e.g., how much to fuse to balance recomputation and memory traffic), which LLMs can articulate, while the compiler ensures legality and supplies fast cost signals. We evaluate on GCN [10] and GraphSAGE [5], showing robust gains and workload-adaptive fusion choices.

Our contributions are:

- An LLM-guided autoscheduler for sparse ML that wraps FuseFlow's fusion-capable sparse ML compiler, enabling arbitrary expression fusion and human-in-the-loop dataflow selection.
- A semi-structured schedule format that the LLM emits and the compiler validates, plus a cost-guided pruning loop using a FLOPs/bytes heuristic.
- An empirical study on sparse models on a simulated dataflow architecture, demonstrating consistent speedups over unfused baselines and parity with hand-tuned/heuristic strategies.

2 Background and Related Work

Dense autoscheduling has matured in systems such as Halide and TVM [13; 2]. Sparse compilers expose formats and scheduling but mostly target CPUs/GPUs and single-expression fusion [11; 1; 14]. Dataflow abstractions and recent sparse-to-dataflow compilers highlight the importance of fusion and dataflow ordering on streaming hardware [8; 7]. Sequence models motivate block-sparse patterns and specialized attention mechanisms [15; 4]. Our work complements this landscape by using an LLM to search the fuse/order space while keeping the compiler itself a black box that guarantees correctness and provides cost signals.

3 Method

3.1 Problem Setting and Interface

We build on FuseFlow [12], a fusion-capable sparse ML compiler implemented within MLIR that: (i) ingests a model graph (Torch-MLIR and MPACT frontends) plus a user *Fuse* schedule; (ii) runs its internal fusion then *enumerates legal dataflow orders* for each fused region; (iii) exposes a FLOPs/byte heuristic that symbolically combines tensor dimensions, sparsity, and intersection rates to estimate operational intensity; and (iv) generates SAM-style dataflow graphs that execute on the Comal simulator or FPGA backends once a schedule is selected.

3.2 LLM-Guided Autoscheduling Loop

Prompt state. We serialize operator types, tensor shapes, sparsity statistics, producer–consumer relations, and known bottlenecks (via coarse roofline classification). In addition, the prompt state captures admissible fuse sets and compiler-enumerated legal execution orders for each fused region. (Tiling and parallelization are treated as *context only* and are not selected by the LLM.)

Proposals and validation. At each iteration, the LLM (i) identifies bottlenecks, (ii) picks a fusion granularity, and (iii) selects a *legal* dataflow order *from* the compiler's set. Outputs use a compact schema; we validate names/shapes and that every order is compiler-legal, then score with the compiler's FLOPs/bytes heuristic. Candidates are ranked by a roofline-style score and pruned; if none pass thresholds, we request alternatives.

Proposal schema. The LLM communicates via a compact JSON-like schema (Listing 1).

Listing 1: AUTOSPARSE proposal schema.

```
Plan := {"rank": int, "score": number, "estimated_OI": number,
        "fusion_groups": [ {"name": string,
                            "ops": [string],
                            "dataflow_order": [string]} ]}
```

3.3 Heuristic and Search Pruning

The heuristic symbolically estimates FLOPs and bytes for a fused loop nest, computes operational intensity (FLOPs/byte), and classifies compute- vs. memory-bound relative to machine balance. Coupled with legal-order enumeration, this yields a small, high-quality candidate set.

3.4 Human-in-the-Loop Selection

When multiple near-ties remain, we surface top-k plans with LLM rationales and heuristic estimates; practitioners may override choices—typically dataflow order—based on dataset-specific sparsity.

3.5 Why LLM-guided vs. solver- or BO-based search

Sparse scheduling spans fusion grouping and legal dataflow orders, forming a large, discrete, hierarchical space with non-smooth objectives (memory-fit thresholds, sparsity-dependent reuse). Exact solvers need brittle encodings and scale poorly; Bayesian Optimization assumes smooth, low-dimensional objectives and struggles here. We instead pair the compiler, which enumerates legal orders and provides a fast FLOPs/bytes signal, with an LLM that proposes structured fusion+order plans; a validator enforces legality and a heuristic score prunes candidates, yielding high sample efficiency. Once structure is fixed, BO/small solvers can tune numeric knobs offline (e.g., tile/parallel factors).

4 Evaluation

Workloads. Two-layer GCN and GraphSAGE on real-world datasets (Table 1).
Backend. We target FuseFlow's Comal simulator [12]: a cycle-accurate dataflow simulator calibrated against a VU9P FPGA implementation with R^2=0.991 agreement. Backend blocking and parallelization are held fixed here to isolate fusion/dataflow order effects.
Baselines. (i) UNFUSED: compiler default with no cross-op fusion; (ii) FULLY FUSED: compiler's greedy fusion/order; (iii) HAND: expert/curated schedule.
LLM configuration. We used GPT-5 (OpenAI) to generate schedule proposals. The model's outputs followed Listing 1's schema and were validated for legality before scoring.

The evaluation on two-layer GCN and GraphSAGE workloads shows that AUTOSPARSE achieves essentially the same performance as the hand-crafted expert schedule. In particular, the reported geomean speedup over a no-fusion baseline is about 1.85x for GCN and 2.22x for GraphSAGE (about 2x overall). By contrast, the fully-fused (greedy) schedule performs very poorly – the LLM-guided plan runs roughly 13-15x faster (geomean) than the fully-fused case – indicating that indiscriminate full fusion greatly inflates memory traffic and hurts performance.

As shown in Figure 3, the fused schedules found by AUTOSPARSE preserve the same total FLOPs as unfused execution but dramatically cut memory traffic. For example, on the largest dataset (OGB-Collab) the GCN model has 1.7 GFLOPs in both cases but bytes drop from 445.9 MiB (unfused) to 186.8MiB (best fused); similarly, GraphSAGE on OGB-Collab goes from 625.2 MiB to 316.4 MiB. This roughly 2x reduction in data movement (with FLOPs unchanged) underlies the speedup gains.

The LLM's search effort is modest (Table 2): per workload, the beam search ran only 9–11 iterations and tested about 28–36 candidate schedules. Only a few dozen configurations were evaluated before converging on the expert-equivalent schedule, suggesting the LLM proposals were close to optimal.

Table 1: Structure of the graph datasets.

Category	Metric	Cora	Cora_ML	DBLP	OGB-Collab
Structure	#Vertex	2708	2995	17716	235868
	#Edge (directed)	10556	16316	105734	2570930
	Feature length	1433-16-7	2879-16-7	1639-16-4	128-16-2

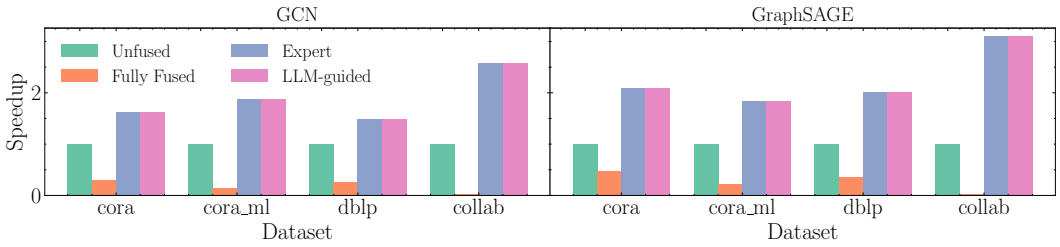

Figure 2: End-to-end speedup (vs. Unfused) for GCN and GraphSAGE on various datasets. The LLM-guided schedule matches the human-expert selection across all datasets and outperforms the unfused and fully fused baselines. Geomean speedup vs. Unfused: **1.85**× (GCN) and **2.22**× (GraphSAGE).

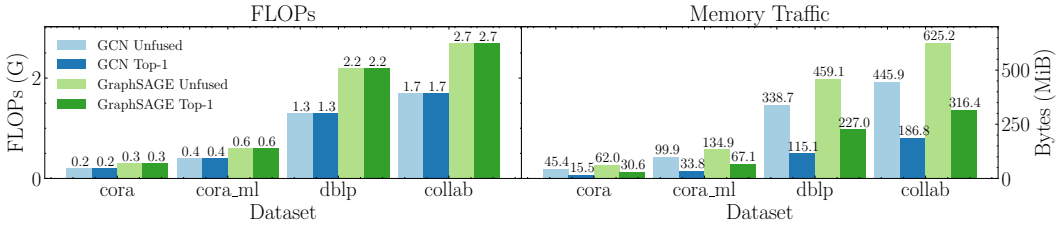

Figure 3: FLOPs (G) and Bytes (MiB) per forward pass. Unfused = no fusion; Top-1 = best fused configuration from the LLM search.

Table 2: Autoscheduler search statistics for GCN and GraphSAGE.

Model	Metric	Cora	Cora_ML	DBLP	OGB-Collab
GCN	Iterations	9	10	11	10
	Tested points	28	30	34	36
GraphSAGE	Iterations	9	10	11	11
	Tested points	28	30	32	36

5 Conclusion

AUTOSPARSE couples an LLM's structural proposals with compiler legality and a cheap cost signal to traverse sparse scheduling spaces. Results across representative workloads indicate the approach is practical and competitive with expert schedules under fixed backend settings. Our dataflow-focused results should transfer to bandwidth-bound accelerators; cache-heavy GPUs would need cache-aware heuristic extensions. The same compiler interface could also drive non-LLM search—e.g., heuristic beam search, simulated annealing, or RL guided by FuseFlow's FLOPs/byte signal—and benchmarking those alternatives is future work.

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